




dAb: Interactive Haptic Painting with 3D Virtual Brushes

William Baxter, Vincent Scheib,
Ming Lin, Dinesh Manocha

UNC Chapel Hill
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dAb != DAB






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Introduction

- Interaction method
- For 2D painting
- Using 3D brush
 - With haptic feedback
 - With deformation
- Palette & paint





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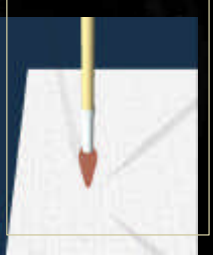




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Introduction


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- **Using 3D brush**
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Introduction

- Interaction method
- For 2D painting
- Using 3D brush
 - With *haptic feedback* →
 - With deformation
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PHANTOM
SensAble Technologies

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Introduction


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- For 2D painting
- Using 3D brush
 - With haptic feedback
 - With *deformation* →
- Palette & paint



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Introduction


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Motivation

Capturing the Sight, Touch, Action and Feeling of Painting

- 3D deformable brush [action]
- Haptic feedback [touch]
- Paint model [sight]
- User interface [action]

[feeling]

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Painting with dAb

- [video]



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Presentation Overview

- Previous Work
- User Interface
- System Organization
- System Components
 - Brush models
 - Force feedback
 - Paint model
- Results

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
- Modeling of Brushes & Strokes
- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
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- User Interface

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Previous Work

- Computer-Generated Painting
 - Meier 96, Curtis et al. 97, Hertzmann 98, Litwinowicz 97
- Modeling of Paint
- Modeling of Brushes & Strokes
- User Interface

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Previous Work

- Computer-Generated Painting
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Previous Work

- Computer-Generated Painting
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- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
 - Curtis et al. '97, Cockshott et al. '92, Hasse & Meyer '92, Kubelka & Munk '31
- Modeling of Brushes & Strokes
- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
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- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
- Modeling of Brushes & Strokes
- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
- Modeling of Brushes & Strokes
 - S. Saito et al. '99, Wong et al. '00, Strassmann '86
- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
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Previous Work

- Computer-Generated Painting
- Modeling of Paint
- Modeling of Brushes & Strokes
- User Interface

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Previous Work

- Computer-Generated Painting
- Modeling of Paint
- Modeling of Brushes & Strokes
- **User Interface**
 - A. R. Smith 78, Painter, Z-Brush, Deep Paint
 - Hanrahan & Haerberli 90, Agrawala et al. 95
 - Johnson et al. 99, Gregory et al. 00

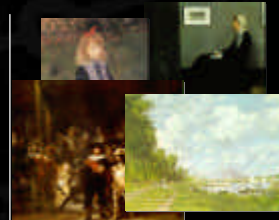
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Motivation Revisited

- The *craft* of painting vs. the *art*



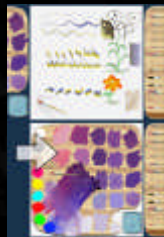
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The dAb Interface

- [video]



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NOTE: when giving presentation,
click in center to progress animation,
click on right edge to advance to next
slide!



System Components

- Brush Model
- Haptic Model
- Paint Model

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System Components

- **Brush Model**
- Haptic Model
- Paint Model

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Brush Model

- Design considerations
 - Interactivity (~30Hz)
 - Unconditional stability
 - Flexibility

Type	Examples
Round	
Flat/Bright	
Filbert	

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Brush Model

- Dynamic model
 - Spring-mass particle system
- Geometric model
 - Subdivision surface

Type	Examples	Model	Structure	Surface
Round				
Flat/Bright				
Filbert				

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Brush Equations

- $F=ma$, or $\begin{pmatrix} \dot{x} \\ \dot{v} \end{pmatrix} = \begin{pmatrix} v \\ M^{-1}f \end{pmatrix}$
- Semi-Implicit numerical integration (Desbrun '99)

$$f = \underbrace{f_l}_{\text{Linear force}} + \underbrace{f_n}_{\text{Non-linear force}}$$

$$\begin{pmatrix} \Delta x \\ \Delta v \end{pmatrix} = \begin{pmatrix} h(v_i + \Delta v) \\ \left(I - h \frac{\partial f}{\partial x} \right)^{-1} h M^{-1} f(x_i) \end{pmatrix}$$

Constant!

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Brush Equations

- Overdamped inertial system
- Eliminate explicit damping
- Solve $F=mv$ (Aristotelian)

$$\Delta x = \left(I - h \frac{\partial f}{\partial x} \right)^{-1} h M^{-1} f(x_i)$$

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System Components

- Brush Model
- **Haptic Model**
- Paint Model

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Haptics

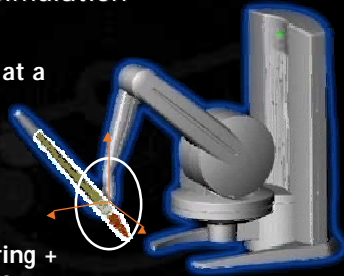
- Simple model
- Designed to run easily at 1kHz
- Decoupled from dynamics
- Effective for control

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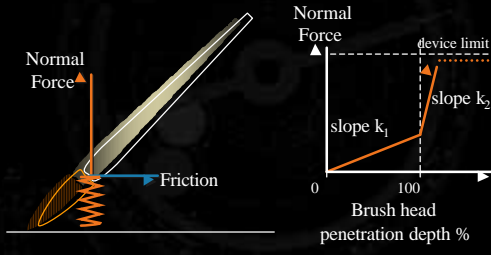
Haptic Simulation

- Force vector at a point
- Linear spring
- Nonlinear spring + angular falloff



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Haptics - Linear



Normal Force

Friction

Normal Force

Brush head penetration depth %

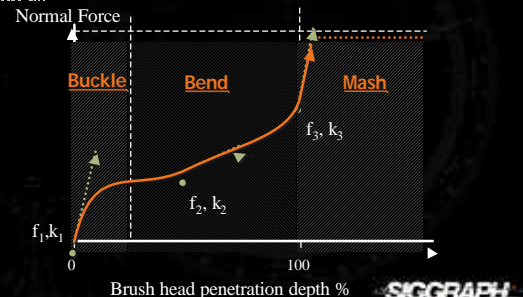
slope k_1

slope k_2

device limit

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Haptics - Non-linear (Spline)



Normal Force

Brush head penetration depth %

Buckle

Bend

Mash

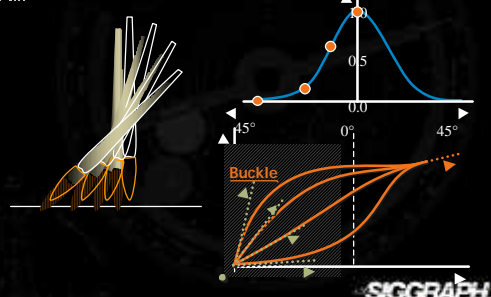
f_1, k_1

f_2, k_2

f_3, k_3

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Haptics - Angular Dependence



Normal Force


Angle

Buckle

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System Components

- Brush Model
- Haptic Model
- Paint Model



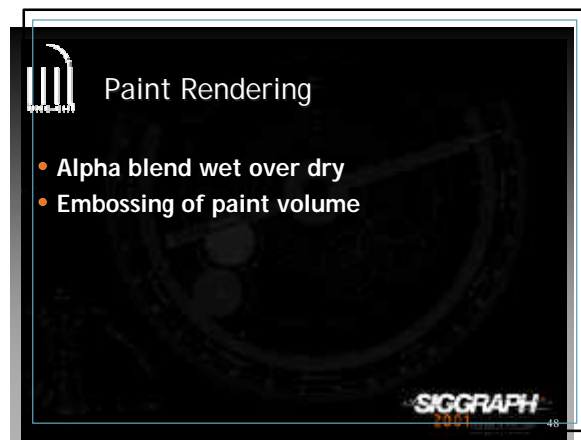
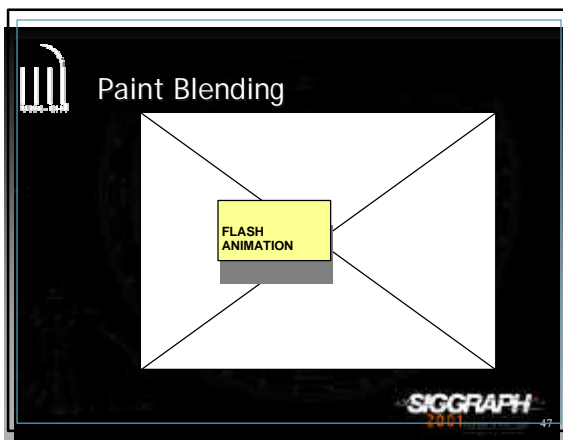
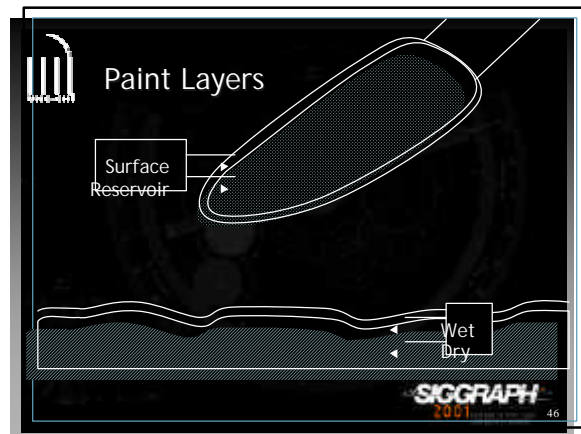
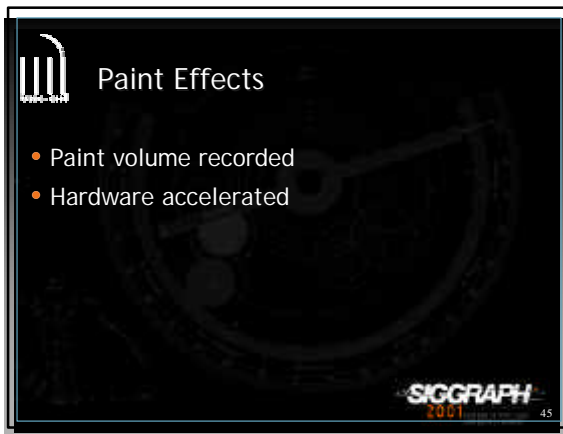
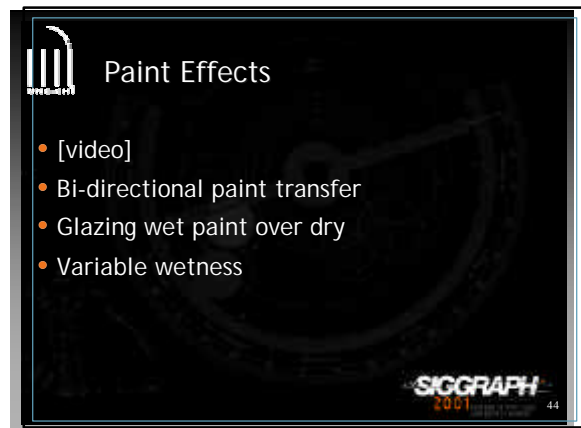
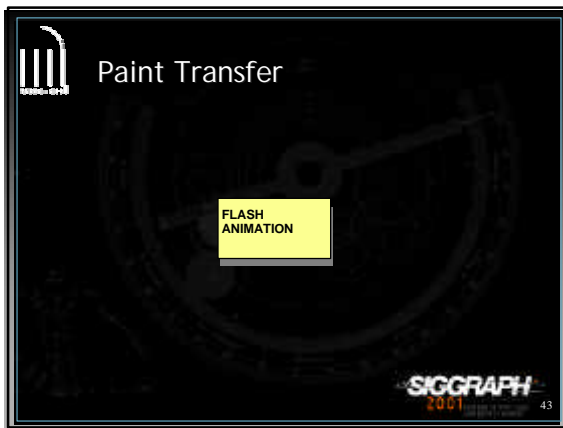
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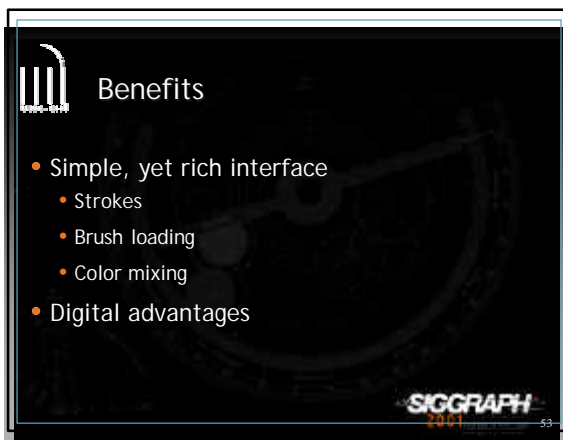
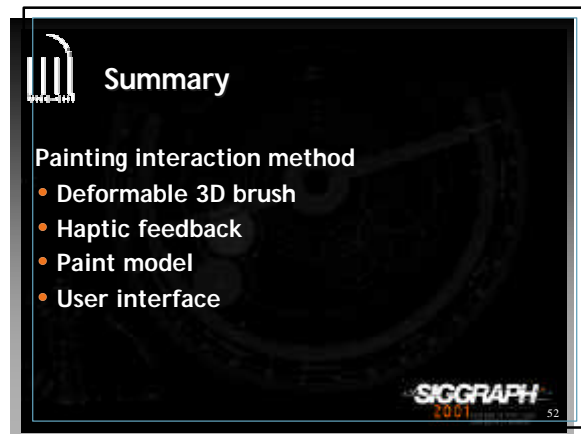
Paint Simulation

- Interactive
- Oil/Acrylic paint
- Take advantage of 3D Brush



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Acknowledgements

• Artists

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Slide Show & Questions

• [Gallery](#)

See dAb in action!
Try it for yourself!
TODAY @ the CAL
from 2-4pm

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Partial Drying

$$C'_{dry} = \frac{a \cdot C_{wet} + (1-a) \cdot C_{dry} - a' \cdot C_{wet}}{(1-a')}; \quad a' = a - da$$

Where :

C_{wet}, C_{dry} are wet & dry color

a, da are wet paint volume & removed volume

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dAb, the happy medium

Non-
painters

Painters



Digital Artists

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